Assumption Grammars: Parsing as Hypothetical Reasoning

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Abstract

A general framework of handling state information for logic programming languages on top of backtrackable assumptions (linear affine and intuitionistic implications ranging over the current continuation) is introduced, with emphasis on its high-level natural language processing abilities. Assumption Grammars (AGs), a variant of Extended DCGs particularly suitable for hypothetical reasoning, and which handles multiple streams without the need of a preprocessing technique, is specified within our framework.

We examine three natural language uses of Assumption Grammars: free word order, anaphora and coordination. We also show two results which were surprising to us, namely: a) Assumption grammars allow a direct and efficient implementation of link grammars—a context-free like formalism developed independently from logic grammars; and b) they offer the flexibility of switching between data-driven or goal-driven reasoning, at no overhead in terms of either syntax or implementation.

Keywords: logic grammars, hypothetical reasoning, state in logic programming, linear affine and intuitionistic implication

1 Introduction

A grammar is a finite way of specifying a language which may consist of an infinite number of sentences. A logic grammar has rules that can be represented as Horn clauses. Logic grammars can be conveniently implemented in Prolog: grammar rules are translated into Prolog rules which can then

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1This paper is based on research first reported in two conference papers [33] and [11] but none of its material has appeared in journal form.
be executed for either recognition of sentences of the language specified, or (with some care) for generating sentences of the language specified.

Different types of logic grammars have evolved through the years, motivated in such concerns as ease of implementation, further expressive power, a view towards a general treatment of some language processing problems, such as coordination, or towards automating some part of the grammar writing process, such as the automatic construction of parse trees and internal representations. Generality and expressive power seem to have been the main concerns underlying all these efforts.

It has been recognized since Colmerauer’s work on Metamorphosis grammars [6] that definite clauses subsume context-free grammars. As the apparently simple translation scheme of grammars to Prolog became popular, DCGs have been assimilated by means of their preprocessor based implementation. When restricted to definite clauses the original DCG translation is indeed operationally trouble free and has a simple Herbrand semantics. On the other hand, mixing DCGs with full Prolog and side effects has been a prototypical Pandora’s box, ever since. Cumbersome debugging in the presence of large list arguments of translated DCGs was another initially unobvious consequence, overcome in part with depth-limited term printing. The complexity of a well-implemented preprocessor made almost each implementation slightly different from all others. The inability to support ‘multiple streams’, although elegantly solved with Peter Van Roy’s Extended DCGs [34], required an even more complex preprocessor and extending the language with new declarations. Worse, proliferation of programs mixing DCG translation with direct manipulation of grammar arguments have worked against data abstraction and portability.

In an apparently distinct line of thought, intuitionistic logic and, more recently linear logic [14] have been influential on logic programming and logic grammars [18]. The result is not only a better understanding of their proof-theoretical characteristics but also a growing awareness on the practical benefits of integrating them in conventional Prolog systems.

This brings us to the initial motivation of this work: we wanted to design a set of powerful natural language processing tools to deal with the complex hypothetical reasoning problems which arise, e.g., when dealing with anaphora resolution, relatives, co-ordination etc. The proposed grammars were also an attempt to deal with the problems of DCGs, while extending their functionality to support multiple streams, as in [34]. Surprisingly, the outcome went beyond the intended application domain. A unified approach to handle backtrackable state information in nondeterministic logic languages, based on a simplified form of linear affine and intuitionistic implications (assumptions) has emerged.

In this paper we examine the natural language uses of our proposed new logic grammar formalism — Assumption Grammars —, which we believe to be the best compromise to date between expressive and linguistic power. We also show two results which were surprising to us, namely: a) Assumption
grammars allow a direct and efficient implementation of link grammars — a context-free like formalism developed independently from logic grammars; and b) they offer the flexibility of switching between data-driven or goal-driven reasoning, at no overhead in terms of either syntax or implementation.

Assumption grammars consist of logic programs augmented with a) multiple implicit accumulators, useful in particular to make the input and output strings invisible, and b) linear and intuitionistic implications scooped over the current continuation (i.e., over the remaining AND branch of the resolution), based on a variant of linear logic [14] with good computational properties [22], affine logic.

The paper is organized as follows: Section 2 surveys the background of logic grammars that is relevant to the present paper; Sections 3 and 4 describe intuitionistic and linear implications and assumptions as a way of representing hypothetical state changes in logic programming; Section 5 gives an example showing the expressive power of assumptions, Section 6 describes Assumption Grammars; Section 7 presents some simple formal language examples, in order to make it easier to follow the natural language examples to be shown later; Section 8 analyses the uses of AGs for three crucial problems in Computational Linguistics (namely, free word order, anaphora and coordination); Section 9 describes implementation techniques for Assumption Grammars; Section 10 briefly describes the notion of Link grammars and shows how directly they can be expressed in terms of AGs; Section 12 discusses related work, and Section 13 presents our conclusions.

2 Background on Logic Grammars

Logic grammars originated with A. Colmerauer’s Metamorphosis Grammars [6]. They consist of rewriting rules where the non-terminal symbols may have arguments, and therefore rule application may involve unification. They can be considered a notational variant of logic programs, in which goal satisfaction is viewed as acceptance of a string by a grammar, and where string manipulation concerns are hidden from the user.

Extraposition Grammars (XGs) [24] allow the interspersing of skips on the left hand side, and these are routinely rewritten in their sequential order at the rightmost end of the rule, e.g.:

```plaintext
rel_marker, skip(X), trace --> rel_pronom, skip(X).
```

In an XG rule, symbols on the left hand side following skips represent left-extraposed elements (e.g., "trace" above marks the position out of which the "noun_phrase" category is being moved in the relativization process).

XGs allow us to describe left-extraposition phenomena powerfully and concisely, and to arrange for the desired representations to be carried on

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2We use our notation for consistency. Pereira’s notation for skip(X) is written "..." on the left hand side and simply left implicit on the right.
to the positions from which something has been extrapolated. Here is for instance Pereira’s extrapolation grammar for the language \(\{a^n b^p c^q\}\):

\[
\begin{align*}
s &\rightarrow as, bs, cs. \\
as &\rightarrow []. \\
as, \text{skip}(x), xb &\rightarrow [a], as, \text{skip}(x). \\
bs &\rightarrow []. \\
bs, \text{skip}(x), xc &\rightarrow xb, [b], bs, \text{skip}(x). \\
cs &\rightarrow []. \\
cs &\rightarrow xc, [c], cs.
\end{align*}
\]

Discontinuous Grammars [7] generalize and include both metamorphosis and extrapolation grammars, by allowing for skips to be arbitrarily rearranged (or duplicated, or deleted) by a rewrite rule. They have been used in particular for implementing adaptations of Chomskyan theories [5]. Here is for instance a discontinuous grammar equivalent to the above extrapolation grammar:

\[
\begin{align*}
s &\rightarrow as, bs, cs. \\
as &\rightarrow []. \\
as &\rightarrow xa, [a], as. \\
bs &\rightarrow []. \\
xa, \text{skip}(x), bs &\rightarrow \text{skip}(x), [b], bs, xb. \\
cs &\rightarrow []. \\
xb, \text{skip}(x), cs &\rightarrow \text{skip}(x), [c], cs.
\end{align*}
\]

In the first grammar, symbols such as \(xb\) can be considered as marks for \(b\)’s which are being left-extrapolated. In the second grammar, such marks can be seen as right-extrapolated. While in this particular example our choice may just be a matter of personal preference, there may be naturalness reasons to prefer a right-extrapolating formulation: some movement phenomena in natural language are more naturally viewed as right rather than left-extrapolation, although they could perhaps be forced into left-extrapolating formulations. Even when this forcing can take place, the resulting impossibility to distinguish between left and right movement creates some theoretical problems (e.g. in the more strict bounding of rightward, as opposed to leftward, movement—see [25]). There may also be efficiency reasons to prefer a right-extrapolating formulation: in our implementation of DGs, the DG above works faster than the XG shown.

The need to refer to skipped substrings explicitly (whether in the XG original notation "...", or in the DG notation \text{skip}(X)) can be avoided altogether when using Assumption Grammars, which handles movements through state changes defensible upon backtracking.

Handling state information in Assumption Grammars is a special case of the general problem of cleanly and efficiently handling state information in declarative languages. We shall therefore examine this next, as well as the related problem of supporting backtrackable state changes.
3 Representing state in logic languages

The main problem is that expressing change contradicts some of the basic principles logic (and functional) languages are built on. By definition, ‘referential transparency’ is lost when a given symbol denotes different objects within the same scope. It has been recognized, however, that this has limited impact on single-threaded data.

3.1 Re-usability of single-threaded data types

Data having a unique producer and a unique consumer are frequent in declarative programming languages. Work on linear types [35], monads [36] and linear language constructs [3] in functional programming has shown that single-threaded objects are subject to *in-place update* within a reasonably clean semantic framework.

In Prolog, the *implicit arguments* of DCG grammars correspond to a chain of variables, having exactly two occurrences each, as in \( a(X_1,X_4) :\sim b(X_1,X_2), c(X_2,X_3), d(X_3,X_4) \). We can see the chain of variables as successive states of a unique object. Clearly, no practical readability problems occur by collapsing such chains having exactly 2 occurrences of each variable. Arguably, reduced visual noise will compensate for keeping in mind that implicit state is passed from one literal to another, when this becomes simply: \( a :\sim b,c,d \).

However, in the presence of *backtracking*, previous values must be kept for use by *alternative* branches. Although irrelevant to the user, for the implementor, this situation conflicts with possibility of *reuse* and makes single-threaded objects more complex in non-deterministic LP languages than in committed choice or functional languages. Our implementation described in subsection 9.1 solves this problem.

3.2 Scope and state

In functional languages like Haskell where, in a deterministic framework, elegant unified solutions have been described in terms of monads and continuations, ‘imperative functional programming’ is used (with relative impunity) for arrays, I/O processing, etc. For non-deterministic logic programming languages like Prolog, the natural *scope* of declarative state information is the current AND-continuation as we want to take advantage of re-usability on a deterministic AND-branch in the resulting tree-oriented resolution process.

This suggests that we need the ability of extending the scope of a state transition over the current *continuation*, instead of keeping it local to the body of a clause. To achieve this our *linear* and *intuitionistic* assumptions will be *scoped* over the current continuation.

**Implementing scope** Once a backtraceable *assume* primitive is implemented with assumptions ranging over the the current AND-branch, it is easy to make unavailable a given assumption to an arbitrary future segment in the current continuation by binding a logical variable serving as a *guard*. This is actually the technique used for BinProlog’s definition of implication:

\[
(C \Rightarrow G) :\sim \text{assume}(\text{Scope},C), \ G, \ \text{Scope}="\$closed".
\]

It ensures, with an appropriate test at *calling time*, that assumption \( C \) is local to the proof of \( G \).\(^3\) Note also that embedded uses require a stack i.e. *asserto-style*

\(^3\)See the actual implementation in file extra.pl of the BinProlog 5.75 distribution, [30].
discipline for the assume operation. Programming with assumptions ranging over the current continuation is exactly the form of hypothetical reasoning described in [31].

4 Hypothetical reasoning with linear and intuitionistic assumptions

This framework will cover a fairly general form of backtrackable state information, which increases the expressiveness of a Prolog system while reducing visual noise due to useless argument passing. Our proposed Assumption Grammars will be derived as an instance of the framework.

4.1 Assumed code, intuitionistic and linear affine implication

We will give a short description of the primitive operations and point out some of the differences with other linear/intuitionistic logic inspired implementations.

Intuitionistic assumei/1 adds temporarily a clause usable in subsequent proofs. Such a clause can be used an indefinite number of times, like asserted clauses, except that it vanishes on backtracking. The assumed clause is represented on the heap.

Its scoped versions Clause => Goal and [File] => Goal make Clause or respectively the set of clauses found in File, available only during the proof of Goal. Clauses assumed with => are usable an indefinite number of times in the proof, e.g. a(13) => (a(X), a(Y)) will succeed.

Linear assumeI/1 adds a clause usable at most once in subsequent proofs. Being usable at most once distinguishes affine linear logic from Girard’s original framework where linear assumptions should be used exactly once. This assumption also vanishes on backtracking. Its scoped version Clause :- Goal\(^4\) or [File] :- Goal makes Clause or the set of clauses found in File available only during the proof of Goal. They vanish on backtracking and each clause is usable at most once in the proof, i.e. a(13) :- (a(X), a(Y)) will fail. Note however, that a(13) :- a(12) :- a(X) will succeed with X=12 and X=13 as alternative answers, while its non-affine counterpart a(13) :- a(12) :- a(X) as implemented in Lolli or Lygon, would fail.

We can see the assumeI/1 and assumeI/1 builtins as linear affine and respectively intuitionistic implication scoped over the current AND-continuation, i.e. having their assumptions available in future computations on the same resolution branch.

4.1.1 On the weakening rule

Two ‘structural’ rules, weakening and contraction are used implicitly in classical and intuitionistic logics. Weakening allows discarding clauses while contraction allows duplicating them.

In Wadler’s formulation of linear logic (based on Girard’s Logic of Unity) they look as follows:

\(^4\)The use of :- instead of the usual :- comes from the fact that in Prolog, an operator mixing alphabetic and special characters would require quoting in infix position. Also, since our linear affine implication differs semantically from usual linear implication, it is reasonable to denote it differently.
\[
\frac{\Gamma, [A], [A] \vdash B}{\Gamma, [A] \vdash B} \text{ Contraction}
\]

\[
\frac{\Gamma \vdash B}{\Gamma, [A] \vdash B} \text{ Weakening}
\]

and do not apply to linear affine (\(\langle \text{A} \rangle\)) assumptions but only to intuitionistic ones (\(\{\text{A}\}\)).

The restrictions on the weakening rule in linear logic require every (linear) assumption to be eventually used. Often, when assumptions range over the current continuation, this requirement is too strong, except for the well-known situation of handling relative clauses through the use of gaps [17]. On the other hand, affine linear logic allows weakening, i.e. proofs might succeed even if some assumptions are left unused.

We found our choice for affine linear assumptions practical and not unreasonably restrictive, as for a given linear predicate, negation as failure at the end of the proof can be used by the programmer to selectively check if an assumption has been actually consumed. It is also possible to check through the addition of a low-level primitive, that at a given point, the set of all affine linear assumptions is empty (cf. our first example in Section 7). This can be made invisible to the user to maintain declarativeness.

### 4.1.2 Implicit sharing/copying conventions

Although intuitionistic logic based systems like λProlog and linear logic implementations usually support quantification with the benefit of additional expressiveness, we have chosen (in compliance with the usual Horn Clause convention) to avoid explicit quantifications, for reasons of conceptual parsimony and simplicity of implementation on top of a generic Prolog compiler.

As linear assumptions are consumed on the first use, and their object is guaranteed to exist on the heap within the same AND-branch, no copying is performed and unifications occur on the actual clause. This implies that bindings are shared between the point of definition and the point of use. On the other hand, intuitionistic implications and assumptions follow the usual ‘copy-twice’ semantics.

### 5 Expressiveness of assumptions

We will show the expressiveness of affine linear assumptions through an example a variant of which has been independently discovered by the creators of the logic language Lygon [38].

**Loop-avoidance in graph walking with linear implication** It is unexpectedly easy to write a linear implication based graph walking program. It will avoid falling in a loop simply because linear implication (\(\mathbf{-}\)) assumes facts that are usable only once (i.e. consumed upon their successful unification with a goal).

\[
\text{path}(X, X, [X]).
\text{path}(X, Z, [X|Xs]) :- \text{linked}(X, Y), \text{path}(Y, Z, Xs).
\]

\[
\text{linked}(X, Y) :- \text{c}(X, Ys), \text{member}(Y, Ys).
\]
\texttt{start(Xs):-}
\texttt{c(1,[2,3]):-c(2,[1,4]):-c(3,[1,5]):-c(4,[1,5]):-}
\texttt{path(1,5,Xs).}

By executing \texttt{-start(Xs)}, we will avoid loops like 1-2-1 and 1-2-4-1 and obtain the expected paths:
\texttt{Xs=[1,2,4,5];}
\texttt{Xs=[1,3,5]}

![Diagram](image)

\textbf{Figure 1: The graph with loops described by c/2}

Note that the adjacency list representation of the graph in fig. 1 ensures that each node represented as a linear assumption \texttt{c/2} becomes unavailable, once visited. This makes our example simpler than the similar program given in the Lygon distribution. Note also that without weakening we would have a hamiltonian walk \footnote{Which, unfortunately, is NP-complete. This is another reason why we have chosen to leave to the programmer the task to forbid weakening only when really needed. It is also interesting to notice, in this context, that propositional (multiplicative, additive, exponential) affine linear logic is decidable \cite{22} while its linear logic counterpart is not.}.

6 Assumption Grammars

We will describe in this section how various forms of assumptions can be used for grammar processing conveniently described as an instance of hypothetical reasoning.

6.1 Description of the Formalism

Assumption Grammars are logic programs augmented with a) linear and intuitionistic implications scoped over the current continuation, and b) implicit multiple accumulators, useful in particular to make the input and output strings invisible.

As a more convenient notation, we shall use the following equivalences in the remainder of the paper:

\texttt{*A:- assumei(A).}
\texttt{+A:- assume1(A).}
\texttt{-A:- assumed(A).}
Hidden accumulators allow us to disregard the input and output string arguments, as in DCGs, but with no preprocessing requirement. They are accessible through a set of BinProlog built-ins, allowing us to define a ‘multi-stream’ phrase/3 construct,

dcg_phrase(DcgStream, Axiom, Phrase)

that switches to the appropriate DcgStream and uses Axiom to process or generate/recognize Phrase. We refer to [32] for their specification in term of linear assumptions.

For reasons that will become apparent later, we will also define, on top of these builtin assumptions, another type called timeless assumptions:

% Assumption:
% the assumption being made was expected by a previous consumption
-\(X:=-\text{wait}(X)\), !.
% if there is no previous expectation of \(X\), assume it linearly
-\(X:+=X\).

% Consumption:
% uses an assumption, and deletes it if linear
-\(X:=-X\), !.
% if the assumption has not yet been made,
% adds its expectation as an assumption
-\(X:+=\text{wait}(X)\).

With these definitions, assumptions can be consumed after they are made, or if the program requires them to be consumed at a point in which they have not yet been made, they will be assumed to be ”waiting” to be consumed (through ”\text{wait}(X)”), until they are actually made (at which point the consumption of the expectation of \(X\) amounts to the consumption of \(X\) itself). Terminal symbols will be noted as: 

#word

6.2 Definition

An assumption grammar is a tuple \(<V_N,V_T,C,A,s,P>\), where \(V_N\) is as usual the non-terminal vocabulary, whose elements are logic terms; \(V_T\) is the terminal vocabulary, whose elements are noted \#t, where t is a logic term; \(C\) and \(A\) are a set of logic program calls \(A=\{+a,*a=a\}\), \(C=\{-a,=a\}\), where a is a logic term, and \{all\_consumed\}; \(s \in V_N\) is the start symbol; and \(P\) are productions of the form: \(n:-\beta\), where \(n \in V_N\) and \(\beta \in \{V_N \cup V_T \cup A \cup C\}^*\).

A sentence in the language defined by an assumption grammar is a sequence of terminals and (possibly empty) elements of \(A\), which are obtained from the start symbol by successive application of production rules, where rule application amounts to rewriting in the case of terminals and non-terminals, as usual, whereas calls from \(A\) and \(C\) range over the current continuation and are such that elements in \(A\) are cancelled by matching elements in \(C\), as follows:

- a call \(+a\) is satisfied by a matching call \(-a\) appearing in its continuation, after which it is no longer available
• a call *a is satisfied by a matching call -a appearing in its continuation, and continues to be available
• a call =a is either satisfied by a matching call -a in its continuation, or satisfies a call -a in whose continuation it appears, after which it is no longer available

Furthermore, a call to consume_all is satisfied if there are no calls left from A and C. Also, as in all Prolog grammars, Prolog calls are allowed in the right-hand side of assumption grammar rules.

We refer to Appendix II for an executable specification of the implicit argument based DCGs of this definition in terms of assumptions and to Appendix I for showing their equivalence to translation based DCGs.

7 Some Formal Language Examples

7.1 $a^n b^n c^n$ revisited

The following AG for the language \{a^n b^n c^n\} is basically the same as the DG shown in Section 2, but does not need to refer to skips explicitly. Markers are now treated as linear assumptions.

\begin{verbatim}
s:- as, bs, cs, all_consumed.  
  
as.  
  as:- #a, +xa, as.  
  
bs.  
  bs:- #b, -xa, +xb, bs.  
  
  

cs.  
  cs:- #c, -xb, cs.  
\end{verbatim}

The predicate all_consumed is used to disallow any leftover assumptions. By defining

\begin{verbatim}
-- X :- \+ -X.
\end{verbatim}

a possible implementation for the present example is:

\begin{verbatim}
all_consumed:- -- xa, -- xb.
\end{verbatim}

From the user’s point of view, program-dependent definitions of all_consumed can be invisibly produced by compilation. For instance, for the example in the next section, the definition will be:

\begin{verbatim}
all_consumed:- --as, --bs,--cs.
\end{verbatim}

Notice that a more declarative programming style results, in that we no longer need to refer to procedural notions such as left or right extrapolation. If a marker xa has been assumed, then it can be consumed upon encountering a corresponding terminal symbol #b.
7.2 A more interesting example — scrambled $a^n b^n c^n$

If we want our strings to retain the same number of a's, b's and c's, but in any order, we can use linear assumptions in a data driven formulation, as follows:

a: - as, !.
   a: + bs, + cs.

b: - bs, !.
   b: + as, + cs.

c: - cs, !.
   c: + as, + bs.

To query, we state for instance:

s: - + as, + bs, + cs, (b,a,c,b,a,c), all_consumed.

with $s$ the start symbol of the grammar. Thus, we start with only one assumption for each of as, bs, cs. Encountering the corresponding terminal symbol (respectively, a, b, c) results in deleting that expectation. But if a terminal, say a, is encountered after its assumption has been consumed, this signals the need to expect a corresponding b and c to appear, so we add the assumptions: +bs, +cs. Therefore the input sequence itself triggers the firing of the rules. In other words, we achieve data-driven behavior. Notice that in order to achieve this data-driven flavor, terminals are used as pseudo-non-terminals, and we no longer note them as #t, but as $t$. String acceptance now reduces to satisfaction of the start state, which contains the input string as a goal.

Here is an even simpler AG formulation, also data driven:

a: = bs.     b: = - bs, = cs.   c: = - cs.
   s: = (a,b,a,b,c,c), all_consumed.

The first assumption, bs, is used to match a's with b's, while cs matches b's with c's, to ensure the same number of each. Notice that by allowing weakening (i.e., by not requesting that all assumptions be consumed at the end) we can obtain a subset of the language, in which for instance the following query succeeds:

s: = (a,a,b,b).

8 AGs and Some Interesting NL Problems

8.1 Free word order

The formal language examples presented suggest a very concise treatment of free word order, a problem that many languages exhibit to some extent. The problem is that since inflections rather than position are used to indicate case or grammatical function, position is used to indicate emphasis or focus, and almost any possible ordering becomes acceptable. For instance, the Sanskrit phrase "Rama pashyati Seetam" (Rama sees Seetam) can also appear as:
This kind of free order of sister constituents, where each retains its integrity, is
easily handled within discontinuous grammars, as shown in [7]. More interesting
is the case in which even the contents of constituents appear to be scrambled up
with elements from other constituents (e.g. as in Warhiri [16, 21]. Even in Latin
or Greek, phenomena such as discontinuous noun phrases, which would appear as
extreme dislocation in prose, are very common in verse (and not unusual even in
certain prose genres, e.g. Plato’s late work, such as the Laws). A contrived example
for Latin would be:

Puella bona puerum parvum amat.
(Good girl loves small boy)

where the noun and adjective in the subject and/or object noun phrase may be
discontinued, e.g.:

Puella Puerum amat bona parvum.

In fact all 5! word permutations are possible, and we certainly do not want to
write a separate rule for each possible ordering.

A DG formulation is shown in ([7]) in which the number of rules needed grows
linearly depending on the number of constituents which can move freely. However,
this formulation resorts of course to explicit naming and manipulation of skipped
substrings. In AGs we can achieve a simpler and more efficient formulation:

amat:- +verb.
puerum:- =noun(acc).  % remove expectation of accusative noun
parvum:- =noun(acc).  % expect accusative noun to match this adj.
bona:- =noun(nom).   % remove expectation of nominative noun
puella:- =noun(nom).  % expect noun in nominative

with queries of the form:
s:- +verb, (bona,puella,puerum,parvum,amat).

8.2 Anaphora

We shall now illustrate how assumption grammars can deal with intersentential
dependencies through the example of anaphora, in which a given noun phrase in
a discourse is referred to in another sentence, e.g. through a pronoun. We refer
to the noun phrase and the pronoun in question as entities which co-specify, since
they both refer to the same individual of the universe.

As a discourse is processed, the information gleaned from the grammar and
the noun phrases as they appear can be temporarily added as hypotheses ranging
over the current continuation. Consulting it then reduces to calling the predicate
in which this information is stored.

We exemplify the hypothesizing part through the following noun phrase rules:
np(X,VP,VP):= proper_name(X), +specifier(X).
np(X,VP,R):= det(X,VP,VP,R), noun(X-F,VP), +specifier(X-F).

pronoun(X-[masc,sing]):= #he.
pronoun(X-[fem,sing]):= #her.
anaphora(X):= pronoun(X).

noun(X-[fem,sing],woman(X)):= #woman.

The linear assumption, +specifier(X), keeps in X the noun phrase's relevant information. In the case of a proper name, this is simply the constant representing it plus the agreement features gender and number; in the case of a quantified noun phrase, this is the variable introduced by the quantification, also accompanied by these agreement features.

Potential co-specifiers of an anaphora can then consume the most likely co-specifiers hypothesized (i.e., those agreeing in gender and number), through a third rule for noun phrase:

np(X,VP,VP):= anaphora(X), -specifier(X).

Semantic agreement can be similarly enforced through the well-known technique of matching syntactic representations of semantic types.

This methodology can of course be extended in order to incorporate subtler criteria. For instance, we can make each pronoun carry, at the end of the analysis, the whole list of its potential referents as a feature. User-defined criteria can then further refine the list of candidate co-specifiers, as in [12].

It is interesting to point out that in order to handle abstract co-specifiers [2], such as events or propositions, all we have to do is to extend the definition so that other parts of a sentence can be identified as possible specifiers as well. For instance, for recognizing “John kicked Sam on Monday” as the co-specifier of “it” in the discourse: “John kicked Sam on Monday. It hurt.”, we can simply make the linear assumption that sentences are potential co-specifiers for pronouns of neuter gender.

8.3 Coordination

Coordination (grammatical construction with the conjunctions "and", "or", "but") has long been one of the most difficult natural language phenomena to handle, because it can involve such a wide range of grammatical constituents (or non-constituent fragments), and ellipsis (or reduction) can occur in the items conjoined. In most grammatical frameworks, the grammar writer desiring to handle coordination can get by reasonably well by writing enough specific rules involving particular grammatical categories; but it appears that a proper and general treatment must recognize coordination as a "metagrammatical" construction, in the sense that metarule, general system operations, or "second-pass" operations such as transformations, are needed for its formulation. Early attempts at such a general treatment [39, 4] were inefficient due to combinatorial explosion. A logic grammar rendition of coordination in terms of logic grammars [8] solved these inefficiencies through the addition of a semantic interpretation component that produced a logical form from the output of the parser and dealt with scoping problems for coordination. In the
following example we show how the syntactic part of a metagrammatical treatment to coordination can be dealt with through AGs.

\[
\text{sent}(\text{and}(S_1,S_2)) \leftarrow s(S_1), + \text{and}, s(S_2).
\]

% conjunction of two sentences - assumes that
% there will be an "and" between them.

\[
s(S) \leftarrow \text{name}(X), \text{verb}(X,P,S), \text{np}(P).
\]

\[
np(P) \leftarrow \text{det}(X,P_1,P), \text{noun}(X,P_1),
\quad = (\text{ref}_\text{np}(P)).
\]

% keep it as potential referent for a missing np
\[
np(P) \leftarrow \# \text{and}, - \text{and},
\quad \% a conjunction appears where an np is
\quad \% expected: consume "and"
\quad = (\text{ref}_\text{np}(P)).
\]

% consume an assumed (or to be assumed) np
% in lieu of the missing one

\[
det(X,P,\text{the}(X,P)) \leftarrow \# \text{the}.
\]

\[
noun(X,\text{cupboard}(X)) \leftarrow \# \text{cupboard}.
\]

\[
\text{name}(\text{tim}) \leftarrow \# \text{tim}.
\]

\[
\text{name}(\text{anne}) \leftarrow \# \text{anne}.
\]

\[
\text{verb}(X,Y,\text{built}(X,Y)) \leftarrow \# \text{built}.
\]

\[
\text{verb}(X,Y,\text{painted}(X,Y)) \leftarrow \# \text{painted}.
\]

For the sentence Tim built and Anne painted the cupboard, for instance, we obtain the semantic representation:

\[
\text{and}(\text{built}(\text{tim},\text{the}(X,\text{cupboard}(X))),\text{painted}(\text{ann},\text{the}(X,\text{cupboard}(X)))
\]

which is just what we intend in this simplified example. Subtler analyses can be implemented as in [12].

## 9 Implementation of Assumption Grammars

### 9.1 High performance implementation of AGs

For reasons of efficiency we have implemented BinProlog's AGs in C. They are accessible through a set of builtins [30]. AGs do not need to represent the chain of existential variables (heap-represented on most WAMs) introduced by the usual DCG and EDCG transformations. Instead, backtrackable destructive assignment implemented with value trailing\(^6\) is used. The built-in #/1 working as the 'connect' relation ?C/3, in DCGs, consumes trail-space only when a nondeterministic situation (choice-point) arises. This is achieved by address-comparison with the top of the heap, saved in the choice-point. By 'stamping' the heap with an extra cell inserted in the reference chain to the value-trailed objects, further attempts to trail

---

\(^6\)Value-trailing consists in pushing both the address of the variable and its value on the trail.
the same address will see it as being above the last choice point. *This actually results in constant heap/trail use for each chain, only when a choice point is created, and no heap/trail use otherwise.*

This is complemented with a very efficient, ‘if-less’ un-trailing operation based on indirect address calculation. Despite the extra run-time effort, as #/1 actually uses a specialized instance of *setarg/3*, the overall performance of this run-time technique is fairly close to the static transformation based approach, even for plain DCGs, while offering multiple-stream functionality. We have also given emulated and native SICStus 2.1.9 figures (DCG-enSP and DCG-natSP) to show that performance is measured w.r.t a fairly efficient DCG processor (DCG-enBP).

The table 1 shows the comparative speed of AGs vs. DCGs on parsing all the well formed expressions of length N=4,5,6, for an arithmetic expression grammar.

### 9.2 Portability: Assumption Grammars in Life

Porting Assumption Grammars to a language which has global variables and back-trackable destructive assignment is easy. Here is the code for Wild-Life. Extending this to multiple dcg streams is straightforward.

```prolog
global(dcg_stream) ?

dcg_def(Xs) :- dcg_stream <- s(Xs).
dcg_val(Xs) :- dcg_stream = s(Xs).
dcg_connect(X) :- dcg_stream = s([X|Xs]), dcg_stream <- s(Xs).
dcg_phrase(Axiom,Xs) :- dcg_def(Xs), Axiom, dcg_val([]).
```

### 10 Assumption Grammars and Link Grammars

It is interesting to note that AGs promote both top-down and data driven thinking in the development of a grammar. We employed the latter in our "data-driven" examples, i.e., those with rules in which a terminal symbol is the left-hand side symbol.

We can exploit the data driven thinking mode for AGs in order to emulate another interesting type of grammars: Link grammars [27].

#### 10.1 Link grammars — informal definition and example

A link grammar consists of a set of terminals (‘words’) each of which has a linking requirement. Planarity (links that do not cross can be drawn over the terminals) and connectivity (all terminal of a recognized phrase can be linked) constraints should be satisfied for each terminal.
The linking requirements of each word are contained in a dictionary. A sample dictionary follows as an illustration:

<table>
<thead>
<tr>
<th>words</th>
<th>formulas</th>
</tr>
</thead>
<tbody>
<tr>
<td>a, the</td>
<td>D+</td>
</tr>
<tr>
<td>ran</td>
<td>S-</td>
</tr>
<tr>
<td>Mary, John</td>
<td>O- or S+</td>
</tr>
<tr>
<td>chased</td>
<td>S- &amp; o+</td>
</tr>
<tr>
<td>snake, cat</td>
<td>D- &amp; (O- or S+)</td>
</tr>
</tbody>
</table>

The linking requirement for each word is expressed as a formula involving the operators & and or. The + or - suffix on a connector name indicates the direction (relative to the word being defined) in which the matching connector (if any) must lie.

The following diagram shows how the linking requirements are satisfied in the sentence “The cat chased a snake”.

![Diagram](image)

### 10.2 A sample translation from Link grammars to Assumption Grammars

The translation into AGs is immediate, considering the representation of link grammar dictionaries shown in the previous section. Below, "+" and "-" have our AG meaning of linear implication and consumption respectively, but with this interpretation they happen to do exactly the same job as the link grammar shown above. All we have to do is to transform the + and - suffixes into prefixes, and add weakening for all predicates being assumed:

a: :- +d.
the: :- +d.

mary: :- -o; +s.
john: :- -o; +s.

chased: :- -s, +o.

snake: :- -d, (-o ; +s).  
cat: :- -d, (-o ; +s).

all_consumed: :- --s, --o, --d.
s: :- (mary, chased, a, snake), all_consumed.

Notice that AGs are descriptively more powerful than Link grammars because as in all logic grammars, their symbols can include arguments, through which we can, for instance, dynamically construct sentence representations as a side-effect of parsing. Conceptually, moreover, we can view AGs as enabling a rendering of link grammars in which the higher-order notion of retractable assumption replaces the more procedural notion of "to the right" or "to the left"
11 Datalog grammars as an instance of Assumption Grammars

Another interesting result is that Assumption Grammars not only render the preprocessor for DCGs obsolete, but can remove the need for a preprocessor for more specialized types of logic grammars, e.g. Datalog grammars [10, 7, 9]. A much shorter interpretation mechanism than the original preprocessor, done in terms of Assumption Grammars, follows:

% CODE: defines advancement in Datalog 'phrase' given as a set of
%   w/3 facts

w(X):-d cg_val(From), w(From,To,X), d cg_def(To).

% this recognizes a phrase From..To

dl g_phrase(From,To):- d cg_def(From), axiom, d cg_val(To).

% DATA: grammar

axiom:-ng,v. ng:-a,n.
a:-w(the). a:-w(a).
n:-w(cat). n:-w(dog).
v:-w(walks). v:-w(sleeps).

% Input phrase in Datalog form

w(0,1,ths).
w(1,2,cat).
w(2,3,walks).

% TEST
?-dl g_phrase(0,3). % will answer yes

Similarly, an Assumption Grammar can be made to work directly on top of file/stream-position information without requiring a special purpose preprocessor.

12 Related Work

Existing work on Linear Logic based Natural Languages processing [17, 1] is mostly at sentence level, while ours covers text level constructs. This is made easy by using hypothetical assumptions which range over the current continuation, instead of locally scoped implications.

Compared with other Linear (Intuitionistic) Logic based systems like Lolli [18, 19], our constructs are implemented on top of a generic Prolog engine. We have chosen to allow weakening but not contraction for linear clauses. Explicit negation as failure applied to facts left over in a proof allows to forbid weakening selectively. We have also chosen to avoid explicit quantifiers, to keep the language as simple as possible. The semantics of our constructs is an instance of the sequent calculus
based descriptions of Horn Clause Logic and the more powerful \textit{uniform proof} based systems of [18]. We can see AGs and accumulator processing in general as an even more specific instance of linear operations.

To avoid passing extra arguments to predicates which do not use them, the accumulator preprocessor of \textit{Wild-Life} 1.01 (based on EDCGs [34]) requires \texttt{pred_info} declarations saying which predicates make use of which accumulators. An advantage of Assumption Grammars, compared with DCGs and EDCGs is that no pre-processing potentially hiding the programmer’s intent at source level is required. This becomes important for easier debugging and direct use of meta-programming constructs.

Also, previous linear logic based approaches to long distance dependencies force us to explicitly code the input and output string in every rule. By using Assumption Grammars we can restore high level expressiveness.

There are other analyses of free-word-order, besides that proposed here, that are also implementable using AGs e.g., using the Chomskyian notion of move-alpha. Move-alpha analysis of free-word-order are typical in Japanese [26, 20, 37]. In recent work, Tanaka uses free word grammars to ‘parse’ electronic circuits and extract known components (transistors etc.) [29]. Equivalent assumption grammars can be used for this type of application as well.

There is some commonality between our approach to co-specifier resolution and the pronoun anaphora approach in the public domain LIFE natural language analyzer, but whereas the Life program is based on antecedence, we use the more general notion of cospecification [28]. Also, while the resolution process in the LIFE program is fixed within the grammar rules (pronoun resolution simply searches the temporally ordered list of potential co-specifiers for the first match on gender, number and semantic type), in our approach, although some matching constraints may be specified in the grammar rules, most are specified lexically. This allows a range of matching constraints and also permits matching on abstract entities.

It is interesting to note that Assumption Grammars provide us with yet another tool for resolving co-specification: the use of multiple accumulators. This approach was investigated in [12].

A recent logic grammar treatment of coordination [9] incorporates work on ellipsis which resorts to the idea of parallel structures [2, 15, 23], but unlike these approaches that stress semantic parallelism, it uses both \textit{syntactic and semantic} parallelism, which can help to automatically determine what the parallel structures are, while the previous approaches can not. It would be interesting to transpose this whole approach to AGs.

\section{Conclusion}

Assumption Grammars, although theoretically no more powerful than previous logic grammars, have more expressive power in that they permit the specification of rewriting transformations involving components of a string separated by arbitrary strings with the sole resource of intuitionistic and (affine) linear assumption scoped over the current AND continuation. Implementation is immediate through BinProlog’s intuitionistic and linear assumptions.

It was surprising to us to discover how directly link grammars could be expressed in AG terms. As well, this discovery motivated us to investigate the data driven mode of AG description, which in itself is another interesting development.
We have presented in a unique framework a set of fairly portable tools for hypothetical reasoning in logic programming languages and used them to specify some previously known techniques, such as Extended DCGs, which have been described in the past only by their implementation.

AGs are useful for writing various programming language processors (compilers, program transformation systems, partial evaluators etc.). They can contribute to the writing of compact and efficient code with very little programming effort.

Compared to previous frameworks based on Linear (Intuitionistic) Logic, ours is portable and runs on top of generic Prolog systems. This is a practical advantage over systems like Lolli or AProlog. Backtrackable destructive assignment, when encapsulated in higher-level constructs simplifies the use of DCGs while offering more powerful facilities in the form of hypothetical assumptions and multiple accumulators. This also reduces the need for explicitly imperative constructs like assert and retract in logic programming languages.

On the implementation side, further research is needed on inferring more, statically, about particular instances of linear and intuitionistic assumptions, which would allow very small overhead over classical statically compiled code. The combination of AGs and linear/intuitionistic assumptions is a practical basis for building semantically clean object oriented extensions on top of Prolog.

An obvious future application is to develop a more encompassing natural language processor using AGs, which incorporates all of the natural language features that were examined in isolation here.

Acknowledgements

We thank for support from NSERC (grants OGP0107411 and 611024), and from the FESR of the Université de Moncton. We also thank Andrew Fall for work reported in [13], summarized here in section 8.2.

References


Appendix I: Accumulator vs. preprocessor based logic grammars

BinProlog’s WAM-level built-in accumulator based grammar processor can be seen as an alternative implementation of preprocessor based DCGs/Extended DCGs. By replacing each occurrence of ‘#’(X) with [X] and each occurrence of :- by --> in each ‘AG grammar rule’ its semantics will be unchanged.

x:- y,#a,z. x --> y,[a],z.
y:- #b,#c. ==> y --> [b],[c]. ==> Prolog
z:- #d,#e. z --> [d],[e].

Alternatively, the reverse translation is usable as a ‘DCG implementation’, with #/1 a WAM-level built-in.

One can be see through the following meta-interpreter (which can be easily customized for either DCGs or the implicit accumulator based component of AGs), that the two are basically alternative implementations of the same abstract algorithm.

interp((A,B),S1,S2):-!, interp(A,S1,S2), interp(B,S2,S3). interp(T,S1,S2):=terminal(T,X),!, connect(X,S1,S2). interp(E,S,S):-empty(E),!.
interp({Goal},S,S):-!, Goal. interp(H,S1,S2):=rule(H,B), interp(B,S1,S2).

DCG instantiation

rule(H,B):= ’-->’(H,B). empty([]).
connect(X,S1,S2):= ’C’(S1,X,S2). terminal([X],X).

AG instantiation

rule(H,B):= clause(H,B). empty(true).
connect(X,[X|S2],S2). terminal(#(X),X).

Appendix II: A specification of AGs as linear affine assumptions

% creates and initializes a named ‘Extended DCG’ stream
ag_def(Name,Xs):-assumed(ag_state(Name,_)),!, assumel(ag_state(Name,Xs)).
ag_def(Name,Xs):-assumel(ag_state(Name,Xs)).

% unifies with the current state of a named ‘DCG’ stream
ag_val(Name,Xs):-ag_state(Name,Xs), assumel(ag_state(Name,Xs)).

% equivalent of the ‘C’/3 step in Prolog
ag_connect(Name,X):=ag_state(Name,[X|Xs]), assumel(ag_state(Name,Xs)).

% EDCG equivalent of phrase/3 in Prolog
ag_phrase(Name,Axiom,Xs,End):-ag_def(Name,Xs), Axiom, ag_val(Name,End).
% file I/O inspired metaphors for switching between streams
ag_tell(Name):-assumed(Name),!,assumed(Name).
ag_tell(Name):-assumed(Name).

ag_telling(Name):-assumed(Name),assumed(Name).
ag_telling(Name):-ag_default(Name).

% projection of previous operations on default DCG stream
ag_default(1).
ag_def(Xs):-ag_telling(Name),!,ag_def(Name,Xs).
ag_def(Xs):-ag_default(Name),ag_tell(Name),ag_def(Name,Xs).

ag_val(Xs):-ag_telling(Name),ag_val(Name,Xs).
ag_connect(X):-ag_telling(Name),ag_connect(Name,X).

ag_phrase(Axiom,Xs,End):-
    ag_telling(Name),ag_def(Xs),ag_phrase(Name,Axiom,Xs,End).

% syntactic sugar for 'connect' relation, in BinProlog 5.75 notation
#W:-ag_connect(W).

% example
axiom:-ng,v. ng:-a,n. a:- #the. a:- #a.
n:- #cat. n:- #dog. v:- #walks. v:- #sleeps.

?-ag_phrase(axiom,Xs,[]).

Xs=[the,cat,walks];
Xs=[the,cat,sleeps];
............
Xs=[a,dog,sleeps]